- Measures magnetic parameters accurately
- Demagnetisation, eddy currents and sample cross-sectional area have been accounted for
- Capable of detecting the number of magnetic phase present in a sample

Introduction

A precise knowledge of various magnetic parameters of ferromagnetic substances, viz. coercivity, retentivity, saturation magnetisation and hysteresis loss, and ability to determine them accurately are important aspects of magnetic studies.

The information about the aforementioned properties can be obtained from a magnetic hysteresis loop which can be traced by a number of methods in addition to the slow and laborious ballistic galvanometer method. Among the typical representatives of AC hysteresis loop tracers, some require the ring form of samples while others can be used with thin lms, wires or even rock samples. Ring form samples are not always practically convenient to make while in others demagnetisation effects sometime become quite important. The present set-up can accept the samples of thin wires of different diameters. The demagnetisation effects, different diameters of samples and eddy currents (due to the conducting property of the material) has been taken into account within the design or graphically.

Design Principle

When a cylindrical sample is placed coaxially in a periodically varying magnetic eld the magnetisation in the sample also undergoes periodic variation. This variation is picked up by a coil, placed coaxially with the sample. For the uniform eld Ha produced, the effective eld H acting in the cylindrical sample will be

$H = H_a \;\; NM$

or $H = H_a - \frac{NJ}{\mu_0}$ (1)

where M is magnetisation, N is normalised demagnetisation factor including 4p and J is the magnetic polarisation de ned by

$B = m0H+J$

with B=mH or m0(H+M) as magnetic induction. The signal corresponding to the applied field, Ha can be written as

$e_1 = C_1 H_a$ (2)

where C_1 is a constant

Further the ux linking with the pick-up coil of area A_c due to sample of area As will be

$$f = m_0(A_c \;\; A_s)H' + A_s B$$

where H′ is the eld in the excess area of the pick-up coil. Under certain conditions this equation reduces to

$$f = m_0 A_c H + A_s J$$

The signal induced in the pick-up coil (e_2) will be proportional to df/dt which after integration yields

$$e_3 = C_3 f = C_3 m_0 A_c H + C_3 A_s J \qquad (3)$$

Solving (1), (2) and (3) gives

$$C_1 C_3 A_s \left(\frac{A_s}{A_c} - N\right) J = C_1 e_3 - \mu_0 C_3 A_c e_1$$

$$C_1 C_3 A_s \left(\frac{A_s}{A_c} - N\right) J = C_3 A_c e_1 - \frac{N C_1 e_3}{\mu_0}$$

Based on these equations the electronic circuit has been designed to give values of J and H and hence the hysteresis loop. Further different magnetic phases present in the sample may also be identi ed by electronically manipulating the pick-up signal.

Description of the set-up

The block diagram of the set-up is given next and a brief description now follows:

Note: Specifications are subject to change.

Tesca Technologies Pvt. Ltd.
IT-2013, Ramchandrapura Industrial Area, Sitapura Extension,
Near Bombay Hospital, Vidhani Circle, Jaipur-302022, Rajasthan, India,
Tel: +91-141-2771791 / 2771792; Email: info@tesca.in, tesca.technologies@gmail.com
Website: www.tescaglobal.com

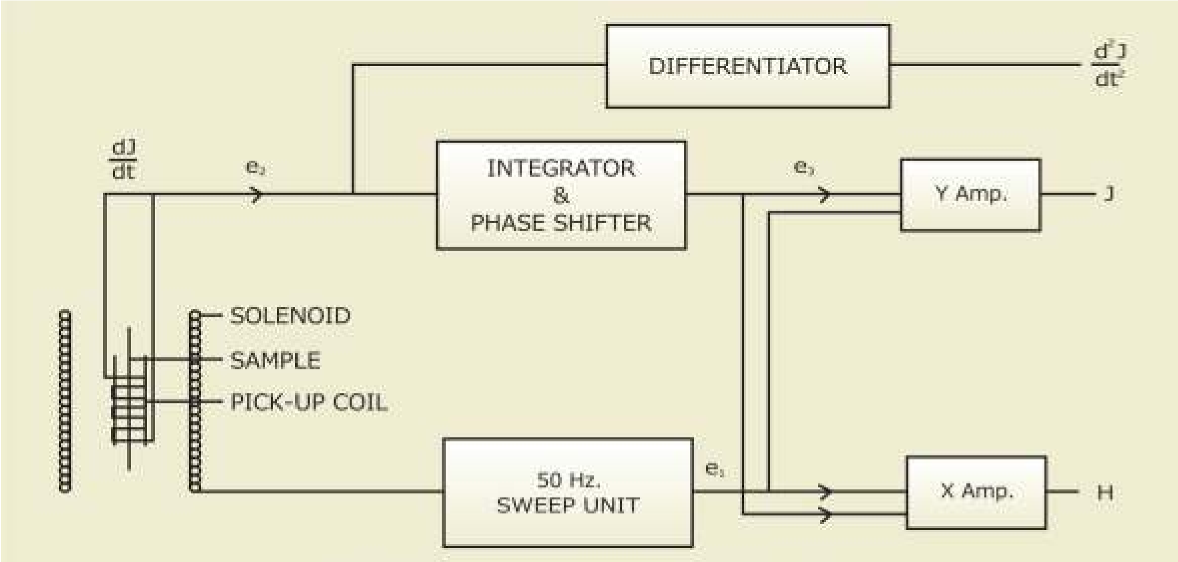


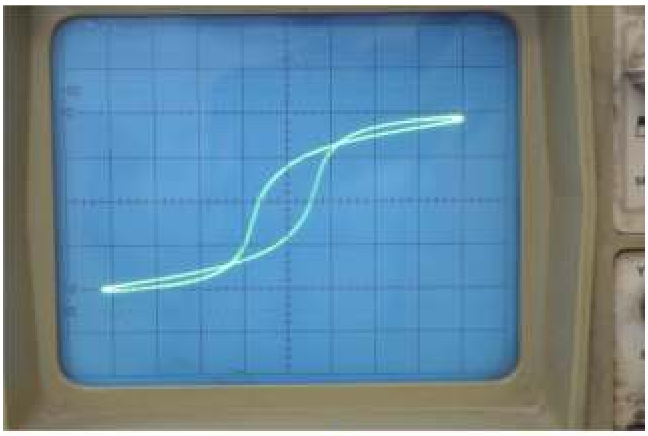
Fig. 1 Block diagram of Hysteresis Loop Tracer

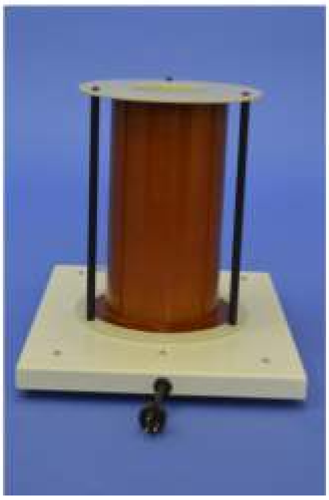
Basic Circuit

The magnetic eld has been obtained with an ac mains driven multilayered solenoid. This magnetic eld has been calibrated with a Hall Probe for uniformity and correspondence with the magnetic eld calculated through ac current passing in the solonoid. A small resistance in series with the solenoid serves the purpose of taking a signal e1 corresponding to H.

The signal e_2 (corresponding to dJ/dt) is taken from the pick-up coil placed at the centre of the solenoid and contains the sample. It is integrated and corrected for phase. This signal is then subtracted from the reference signal e1 and ampli ed to give the signal corresponding to J. The e1 signal is also subtracted from $3e_3$ in correct ratio (to account for demagnetisation and area ratio) and amplified to give signal corresponding to H.

e_2 is also passed through the differentiator for getting signal
2
corresponding to d^2J/dt_2 which is used for phase identification.





Applications

The following magnetic parameters can be measured by this set-up:

- Coercivity
- Retentivity
- Saturation magnetisation
- Various magnetic phase identi cation
- Hysteresis loss

The equipment is complete in all respect, including a set of samples (wires of Nickel, and different grades of iron etc.).

A Cathode Ray Oscilloscope will however be required.

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Tel: +91-141-2771791 / 2771792; Email: info@tesca.in, tesca.technologies@gmail.com
Website: www.tescaglobal.com